



# **Personalizing CS1 with Robots**

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Daniel Walker, Lijun Ni, Doug Blank, Tucker Balch

## I'd like to thank the academy..

- This paper would not be possible without the following assistance:
  - Deepak Kumar – Wrote the book!
  - Keith O'Hara – Programmed the Fluke!
  - Daniel Walker – Built the Fluke!
  - Doug Blank – Wrote the Software!  
(& current IPRE Director)
  - Tucker Balch – Made us do it!  
(past IPRE director)
  - Microsoft Research – Provided the Funding!

# Institute for Personal Robots in Education (IPRE)

- IPRE is a joint effort between Georgia Institute of Technology and Bryn Mawr College, sponsored by Microsoft Research.
- IPRE has developed an (inexpensive) robot platform, (free) textbook, and (free) curriculum, that use personal robots to teach CS1.
- This talk is not about IPRE, for more information see:

[www.RobotEducation.org](http://www.RobotEducation.org)

# This talk does not replace the paper!

- In this talk I will be covering what it is like to teach using personal robots.
- Read the paper for more in-depth coverage on the following topics:
  - The Hardware
  - Myro – The software
  - Our free textbook!
  - Our curriculum
  - Early results
  - Future Work

## We have some experience teaching with robots...

- As part of the IPRE development, Georgia Institute of Technology and Bryn Mawr College have have test taught **TEN** (10) CS 1 with robots classes starting in Spring 2007
- GaTech – 66% male
- Bryn Mawr – 99% female
- I have taught 4 semesters (5 classes)
  - Summer 2007 – 25 students
  - Fall 2007 – 110 students
  - Fall 2008 – 265 students (2 sections)
  - Spring 2009 – 130 students

## Teaching CS1 with “context” - The Personal Robot

- Teaching CS1 with a robot, not teaching robotics.
- Assumption: Teaching CS1 using some form of context is good.
- IPRE's context is a personal robot.

## Student ownership (at least for a semester)

- Students purchase and own their robot.

or...

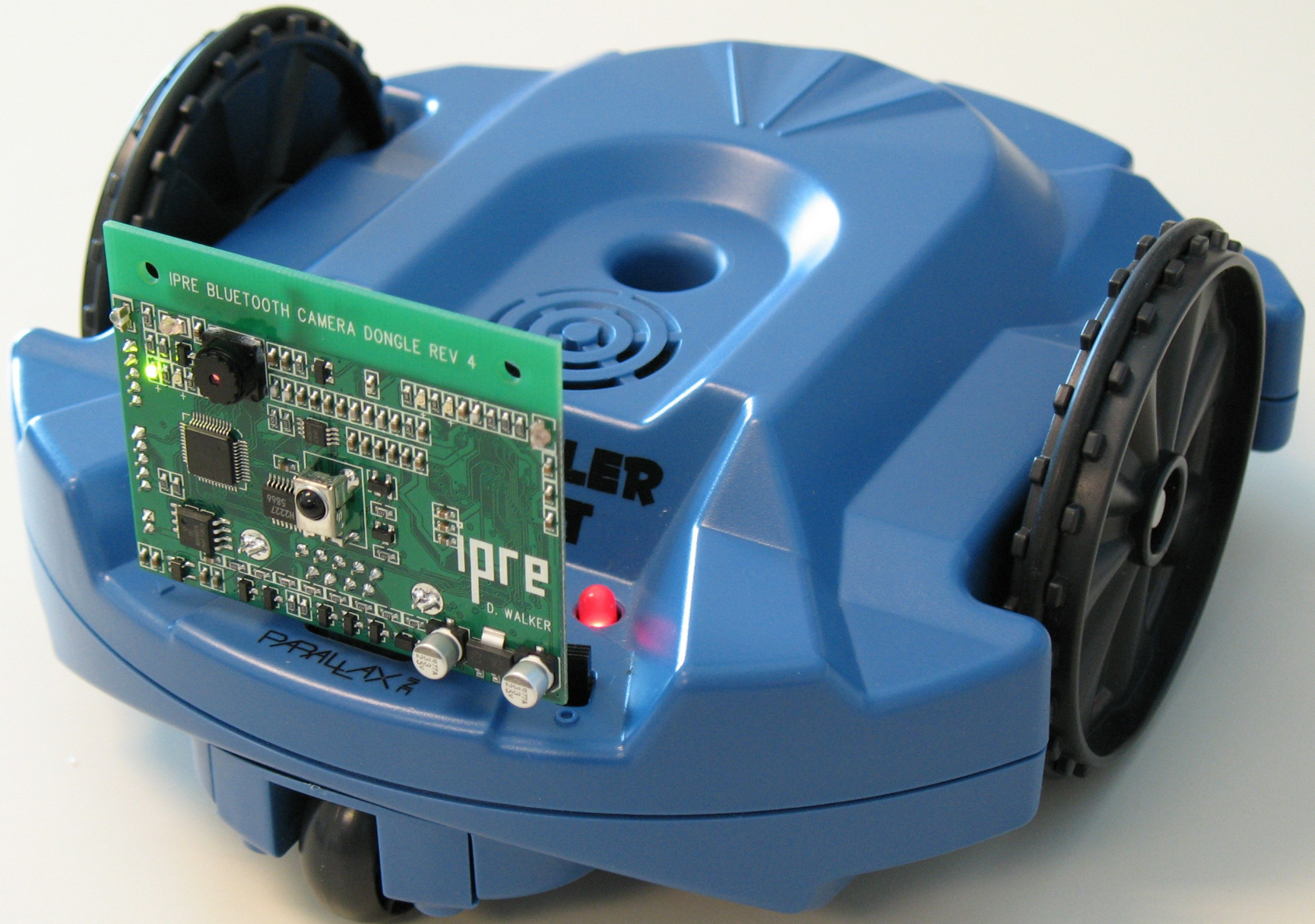
- Students “check-out” a robot for the entire class, and can take it home.

As opposed to...

- A lab of robots that students get to use during “approved class time”.

## Scribbler Robot with Fluke

- Inexpensive enough so that every student has their own (\$150-\$200)
- Small enough to carry to class, dorm rooms, and home.
- Robust enough to carry to class, dorms...
- Cute and non-threatening.



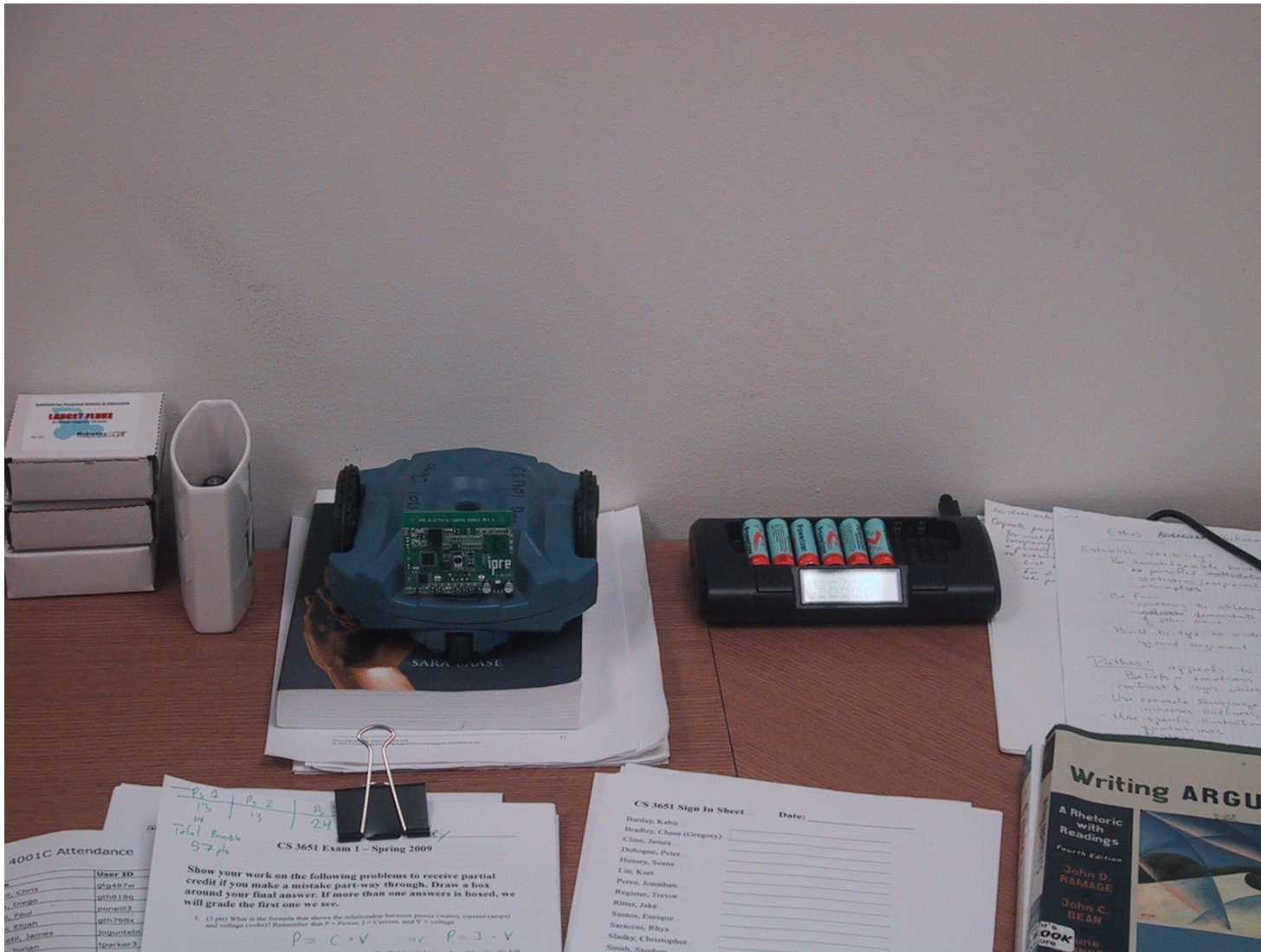
IPRE BLUETOOTH CAMERA DONGLE REV 4

IPRE  
D. WALKER

PARALLAX

# Impact on the Instructor

- You need a robot, and batteries, and Bluetooth for your computer.



## Oh yes, and a little bit of knowledge...

- Myro currently only supports Python (Teaching CS1 with python is joyful!)
- Others have built Myro-like systems in, C++ and Scheme, etc....
- Next version of Myro runs on top of the CLR ( .Net / Mono) so any CLR language will work! [ IronPython, C#, Java (ikvm.net), IronScheme, Ada (A#) etc...]
- And you have to learn a little about the hardware...

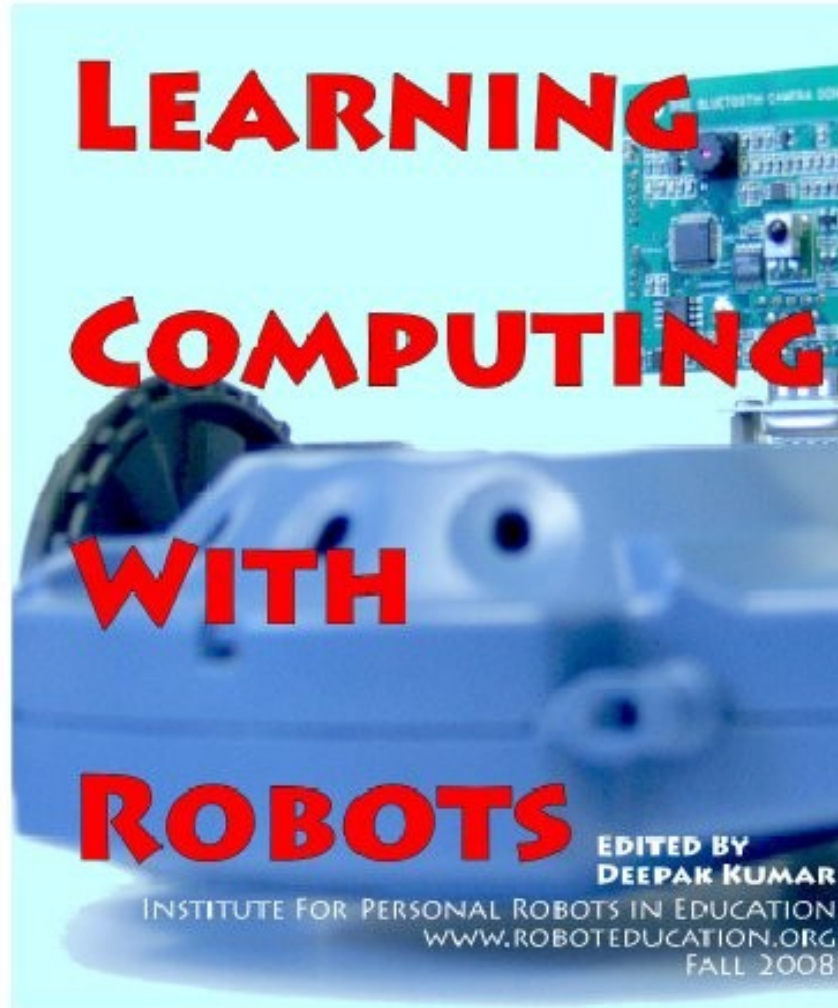
# Myro/Robot/Python demo!

## You may also want some curriculum material...

- Robot Assignments:
  - Make it sing and dance
  - Avoid Walls
  - Find the lamp
  - Find the yellow target
  - Create special FX (manipulate pixels in camera images)
  - Create robot movies (robot actors, camera robots)
  - Put on a live robot performance
- Robot themed test problems

**[wiki.RobotEducation.org](http://wiki.RobotEducation.org)**

# Free Textbook



[wiki.RobotEducation.org](http://wiki.RobotEducation.org)

# wiki.RobotEducation.org/Educator\_Resources

Educator Resources - IPRE Wiki - Mozilla Firefox

File Edit View History Bookmarks Tools Help

ipre http://wiki.roboteducation.org/Educator\_Resources

- Printable version
- Permanent link

| Topic                     | Powerpoint  | Lecture Notes                                | Activities/Resources  | Assignments  |
|---------------------------|---|--|---|--|
| Introduction to Computing | <a href="#">Media:ShortHistoryOfComputing.ppt</a>   |  |   |  |
| Introduction to the Robot | <a href="#">Media:robotIntroduction.ppt</a><br><a href="#">Media:ComputingAndRobots.pdf</a> | <a href="#">Media:robotIntroduction.pdf</a>  | <a href="#">Media:Lab1.pdf</a>  |  |
| Algorithms                | <a href="#">Media:theAlgorithm.ppt</a>  |  |   |  |
| Variables, Types & Math   | <a href="#">Media:variablesTypesMath.ppt</a>  | <a href="#">Media:VariablesTypesMath.pdf</a> |   |  |
| Functions                 | <a href="#">Media:Functions.ppt</a>   | <a href="#">Media:functions.pdf</a>          |   |  |
| Robot Sensors             | <a href="#">Media:robotSensors.ppt</a>  |  | <a href="#">Sensor-Video.mpeg</a>   | <a href="#">RobotColorArena.pdf</a><br><a href="#">Media:AvoidWallAssignm</a>  |
| Behavior based Control    | <a href="#">Media:behavior.ppt</a>  |  | <a href="#">Media:behaviors.pyw</a><br><a href="#">Behaviors1.mpeg</a><br><a href="#">Behaviors2.mpeg</a>   |  |
| Images & Computer Vision  | <a href="#">Media:images.ppt</a>  |  | <a href="#">media:findWall.pyw</a><br><a href="#">cv1.mpeg</a> <a href="#">cv2.mpeg</a><br><a href="#">cv3.mpeg</a>   | <a href="#">media:findYellowWall.do</a><br><a href="#">RobotColorArena.pdf</a> |
| Reading Barcodes          | <a href="#">Media:Barcodes.ppt</a>  |  | <a href="#">media:scan_barcodes.pyw</a><br><a href="#">media:barcode_color.gif</a><br><a href="#">media:BarcodesAE.doc</a><br><a href="#">barcode1.mpeg</a><br><a href="#">barcodes2.mpeg</a><br><a href="#">barcodes3.mpeg</a> | <a href="#">Free Barcode Generato</a>  |
| ...                       |   |  |   |  |
| Mid-Class Python Review   | <a href="#">Media:python-review1.ppt</a><br><a href="#">Media:python-review2.ppt</a>        |  | <a href="#">review1.mpeg</a><br><a href="#">review2.mpeg</a>  |  |
| JavaScript for            |   |  | <a href="#">[Alert Box]</a>   |  |

Done

## Concrete Student Output

- Students know that their peers will be watching when they demo their assignments.
- Assignments produce deliverables they want to show to their friends, siblings, even parents!
- Movies they can share with grandma over the Internet!

# Videos of Student Projects

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## Some Early Results

| Fall '07 Class | Success Rate | Students    |
|----------------|--------------|-------------|
| Robots         | 90.97%       | 131 of 144  |
| NonRobots      | 85.71%       | 78 of 91    |
| MediaComp      | 73.06%       | 179 of 245  |
| MATLAB         | 69.16%       | 740 of 1070 |

## Take Home Points

- Students find the robots very motivating!
- Robots are fun, and not at all scary!  
(And the students are not afraid of them either!)
- Support material is available to make this easy!
- Go read the paper!
- Come talk with us!

# Thank you!

- Questions?

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**www.RobotEducation.org**